

On propositional program equivalence

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Program equivalence

```
if  $x = 1$  then  
  |  $y++$ ;  
else  
  |  $z := z/2$ ;  
end
```

$\equiv$

```
if  $x \neq 1$  then  
  |  $z := z/2$ ;  
else  
  |  $y++$ ;  
end
```

Propositional program equivalence

```
if b then  
  | p;  
else  
  | q;  
end
```

≡

```
if not b then  
  | q;  
else  
  | p;  
end
```

Program equivalence

```
s := new stack();
node := root;
while node != nil do
  | s.push(node);
  | node := node.left;
end
while !s.empty do
  | node = s.pop();
  | visit(node);
  | node = node.right;
  | while node != nil do
    | | s.push(node);
    | | node := node.left;
  | end
end
```

≡

```
s := new stack();
node := root;
while node != nil or !s.empty do
  | if node != nil then
  | | s.push(node);
  | | node = node.left;
  | else
  | | node = s.pop();
  | | visit(node);
  | | node = node.right;
  | end
end
```

(courtesy of Hendrik Jan Hoogeboom)

Propositional program equivalence

```
s;  
while b do  
| p;  
end  
while c do  
| q;  
| while b do  
| | p;  
| end  
end  
end
```

=

```
s;  
while b or c do  
| if b then  
| | p;  
| else  
| | q;  
| end  
end  
end
```

Fix a set $\Sigma = \{p, q, \dots\}$ of **actions** and a set $T = \{s, t, \dots\}$ of **tests**

$$\text{BExp} \ni b, c ::= t \in T \mid b + c \mid b \cdot c \mid \bar{b}$$

$$\text{KExp} \ni e, f ::= b \in \text{BExp} \mid p \in \Sigma \mid e + f \mid e \cdot f \mid e^*$$

- Language semantics in terms of *guarded strings*:

$$\alpha_1 p_1 \alpha_2 p_2 \alpha_3 p_3 \cdots \alpha_n p_n \alpha_{n+1}$$

where $\alpha_i \in 2^T$ and $p_i \in \Sigma$. For example:

$$\llbracket t \rrbracket = \{\alpha \in 2^T : t \in \alpha\} \quad \llbracket e + f \rrbracket = \llbracket e \rrbracket \cup \llbracket f \rrbracket \quad \llbracket e \cdot f \rrbracket = \{w\alpha x : w\alpha \in \llbracket e \rrbracket, \alpha x \in \llbracket f \rrbracket\}$$

- We can embed simple propositional programs:

$$\text{if } b \text{ then } e \text{ else } f \mapsto b \cdot e + \bar{b} \cdot f$$

$$\text{while } b \text{ do } e \mapsto (b \cdot e)^* \cdot \bar{b}$$

Fix a set $\Sigma = \{p, q, \dots\}$ of **actions** and a set $T = \{s, t, \dots\}$ of **tests**

$$\text{BExp} \ni b, c ::= t \in T \mid b + c \mid b \cdot c \mid \bar{b}$$

$$\text{KExp} \ni e, f ::= b \in \text{BExp} \mid p \in \Sigma \mid e + f \mid e \cdot f \mid e^*$$

- ▶ Complete, quasi-equational axiomatization of equivalence.
- ▶ Equivalence is decidable (via automata), but PSPACE-hard.
- ▶ **However**: in practice, this scales rather well!
- ▶ Most practical programs encoded in KAT are deterministic.

Fix a set $\Sigma = \{p, q, \dots\}$ of **actions** and a set $T = \{s, t, \dots\}$ of **tests**

$\text{BExp} \ni b, c ::= t \in T \mid b + c \mid b \cdot c \mid \bar{b}$

$\text{GExp} \ni e, f ::= \text{assert } b \mid p \in \Sigma \mid e \cdot f \mid \text{if } b \text{ then } e \text{ else } f \mid \text{while } b \text{ do } e$

- ▶ Language semantics in terms of *guarded strings*.
- ▶ Language equivalence is efficiently decidable! (nearly linear)

GKAT semantics

By example

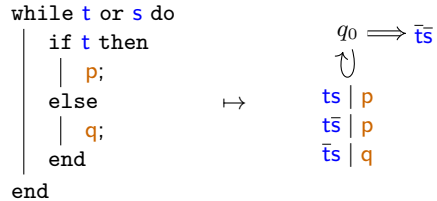
$$\left[\begin{array}{l} \text{if } t \text{ then} \\ \quad | \quad p; \\ \text{else} \\ \quad | \quad q; \\ \text{end} \end{array} \right] = \left\{ \begin{array}{l} tpt, \\ t\bar{p}\bar{t}, \\ \bar{t}q\bar{t}, \\ \bar{t}qt \end{array} \right\}$$

GKAT semantics

By example

$$\left[\begin{array}{l} \text{while } t \text{ or } s \text{ do} \\ | \quad \text{if } t \text{ then} \\ | | \quad p; \\ | \quad \text{else} \\ | | \quad q; \\ | \quad \text{end} \\ \text{end} \end{array} \right] = \left\{ \begin{array}{l} \bar{t}\bar{s}, \\ \bar{t}sqt\bar{s}, \\ \bar{t}spt\bar{s}q\bar{s}, \\ \dots \end{array} \right\}$$

GKAT decision procedure



See (Smolka et al. 2020) for the full details.

GKAT decision procedure, cont'd

Theorem (Smolka et al. '20)

For every GKAT expression e , we can construct a GKAT automaton A_e such that $\llbracket e \rrbracket = \llbracket A_e \rrbracket$.

This is a basic syntax-directed translation, à la (Thompson 1968).

Lemma

A_e is at most linear in the size of e .

Equivalence (bisimilarity) of GKAT automata can be easily decided.

GKAT axiomatization

Are there rules that characterize when $\llbracket e \rrbracket = \llbracket f \rrbracket$?

We will use the condensed syntax:

$$\text{GExp} \ni e, f ::= b \in \text{BExp} \mid p \in \Sigma \mid e \cdot f \mid e +_b f \mid e^{(b)}$$

Order of operations: first $-^{(b)}$, then $\cdot$, then $+_b$.

GKAT axiomatization, cont'd

Conditionals

$$e +_b e = e$$

$$e +_b f = f +_{\bar{b}} e$$

$$(e +_b f) +_c g = e +_{b \cdot c} (f +_c g)$$

$$e +_b f = b \cdot e +_b f$$

Composition

$$0 \cdot e = e \cdot 0 = 0$$

$$1 \cdot e = e \cdot 1 = e$$

$$e \cdot (f \cdot g) = (e \cdot f) \cdot g$$

$$(e +_b f) \cdot g = e \cdot g +_b f \cdot g$$

Loops

$$e^{(b)} \cdot f = e \cdot (e^{(b)} \cdot f) +_b f$$

$$(e +_b 1)^{(c)} = (b \cdot e)^{(c)}$$

$$\frac{g = e \cdot g +_b f \quad e \text{ productive}}{g = e^{(b)} \cdot f}$$

...and **generalizations** of the above

Open Question #1

Do we need the **generalized loop rules**?

Open Question #2

Can we factor out the **side condition**?

Theorem (Smolka et al. '20)

For all GKAT expressions e and f , we have $\llbracket e \rrbracket = \llbracket f \rrbracket$ if and only if $e = f$ follows from the rules above.

GKAT axiomatization, cont'd

Complete algebraic axiomatization of KAT goes back to Kozen (1996)...

GKAT programs are a proper subset of KAT programs...

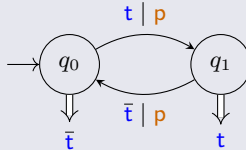
So what makes GKAT so difficult?

GKAT expressivity

Every finite automaton corresponds to a regular expression...

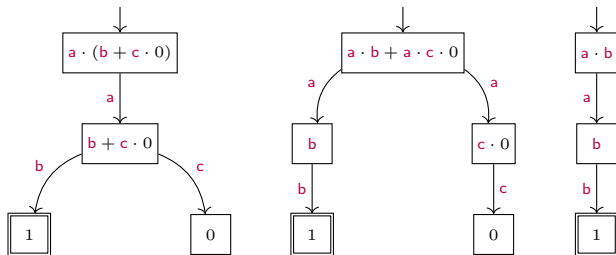
...but not every GKAT automaton corresponds to a GKAT program!

Example (Kozen & Tseng 2008; Schmid, K., Kozen & Silva 2021)



A detour through process algebra

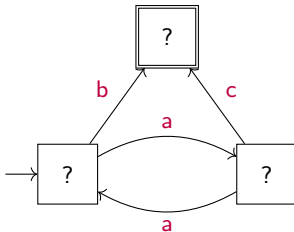
Milner studied *regular expressions up to bisimilarity* in 1984.



He proposed axioms for equivalence, but left completeness open.

A detour through process algebra

Not all behaviors realized as expressions (Milner 1984; Bosscher 1997)



But there is an axiomatization for fragment *without 1* (Grabmayer & Fokkink 2020)

$$0 \mid \mathbf{a} \mid e + f \mid e \cdot f \mid e^* f$$

Skip-free GKAT

The *skip-free fragment* of GKAT is given by

$$\text{GExp}^- \ni e, f ::= 0 \mid p \mid e +_b f \mid e \cdot f \mid e^{(b)} f$$

- Every skip-free expression satisfies the **side condition**!

$$\frac{g = e \cdot g +_b f \quad e \text{ productive}}{g = e^{(b)} \cdot f} \implies \frac{g = e \cdot g +_b f}{g = e^{(b)} f}$$

Skip-free GKAT axiomatization

Conditionals

$$e +_{\mathbf{b}} e = e$$

$$e +_{\mathbf{b}} f = f +_{\overline{\mathbf{b}}} e$$

$$(e +_{\mathbf{b}} f) +_{\mathbf{c}} g = e +_{\mathbf{b} \cdot \mathbf{c}} (f +_{\mathbf{c}} g)$$

Composition

$$0 \cdot e = e \cdot 0 = 0$$

$$e \cdot (f \cdot g) = (e \cdot f) \cdot g$$

$$(e +_{\mathbf{b}} f) \cdot g = e \cdot g +_{\mathbf{b}} f \cdot g$$

Loops

$$e^{(\mathbf{b})} f = e \cdot (e^{(\mathbf{b})} f) +_{\mathbf{b}} f$$

$$\frac{g = e \cdot g +_{\mathbf{b}} f}{g = e^{(\mathbf{b})} f}$$

Completeness Theorem

(K., Schmid & Silva 2023)

For e, f skip-free GKAT expressions, the following are equivalent:

1. e and f are language equivalent
2. $e = f$ is provable from these axioms

This is an *algebraic* and *finitary* axiomatization!

Skip-free GKAT axiomatization

Completeness Theorem (K., Schmid & Silva 2023)

For e, f skip-free GKAT expressions, the following are equivalent:

1. e and f are language equivalent
2. $e = f$ is provable from the axioms

Proof sketch.

We designed two transformations:

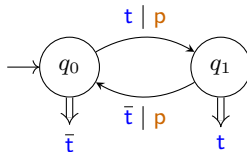
- ▶ gtr : Skip-free GKAT expressions $\rightarrow$ fragment of 1-free regex
- ▶ rtg : fragment of 1-free regex $\rightarrow$ skip-free GKAT expressions

Given 1-free GKAT expressions e and f with $\llbracket e \rrbracket = \llbracket f \rrbracket$:

$$\llbracket gtr(e) \rrbracket = \llbracket gtr(f) \rrbracket \implies gtr(e) \equiv gtr(f) \implies rtg(gtr(e)) \equiv rtg(gtr(f)) \implies e \equiv f \quad \square$$

More control flow operators

Remember this automaton?

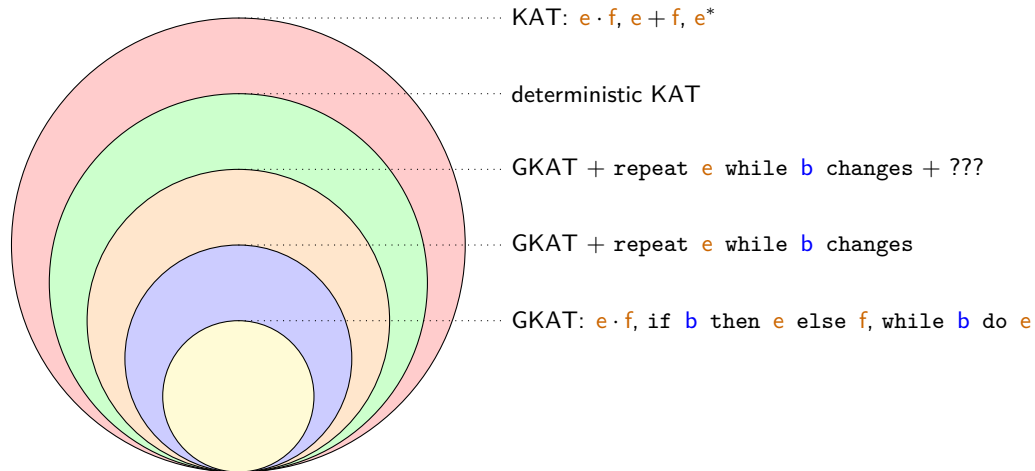


A pseudo-expression for this could be

if t then {repeat p while t changes} else assert 1

What if we add repeat e while b changes as an operator to GKAT?

A hierarchy



A hierarchy

Theorem (Ten Cate & K. '25)

For any deterministic fragment of KAT with finitely many operators ($e \cdot f$, if b then e else f , while b do e , ...), there exist a deterministic KAT expression outside this fragment.

Goto removal

```
L:
  if t then
    | p;
    goto R;
  return;
R:
  if not t then
    | q;
    goto L;
  return;
```

goto removal
(e.g., calipso)

```
x := 1;
while x ≠ 0 do
  | if x = 1 and t
  | then
  |   | p;
  |   x := 2;
  | else if x = 2 and
  |   not t then
  |   | q;
  |   x := 1;
  | else
  |   x := 0;
end
```

See (Erosa & Hendren '94; Cassé et al. '02)

(De)compilation

```
L:
if t then
|  p;
|  goto R;
return;
R:
if not t then
|  q;
|  goto L;
return;
```



executable



```
while t do
|  p;
|  if t then
|  |  break;
|  q;
end
```

Enter CF-GKAT

Fix sets of:

- ▶ *actions* $p \in \Sigma$;
- ▶ *tests* $b \in T$;
- ▶ *labels* $\ell \in L$; and
- ▶ *indicator values* $i \in I$.

CF-GKAT is GKAT augmented with non-local flow control:

$$\text{GExp} \ni e, f ::= \text{assert } b \mid p \in \Sigma \mid x := i \ (i \in I) \mid e; f \mid \text{if } b \text{ then } e \text{ else } f \mid \\ \text{while } b \text{ do } e \mid \text{break} \mid \text{return} \mid \text{goto } \ell \ (\ell \in L) \mid \text{label } \ell \ (\ell \in L)$$

See also (Kozen '08) for how to do this in KAT.

CF-GKAT semantics

By example

$$\left[\begin{array}{l} \text{while } t \text{ do} \\ \quad p; \\ \quad \text{if } t \text{ then} \\ \quad \quad \text{break;} \\ \quad q; \\ \text{end} \end{array} \right] = \left\{ \begin{array}{l} t\bar{p}tq\bar{t}, \\ t\bar{p}tqt\bar{p}tq\bar{t}, \\ tpt \\ t\bar{p}tqtpt \\ \dots \end{array} \right\}$$

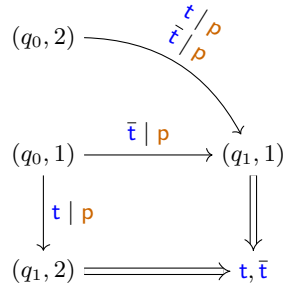
$$\left[\begin{array}{l} L: \\ \text{if } t \text{ then} \\ \quad p; \\ \quad \text{goto } R; \\ \text{return;} \\ R: \\ \text{if not } t \text{ then} \\ \quad q; \\ \quad \text{goto } L; \\ \text{return;} \end{array} \right] = \left\{ \begin{array}{l} tpt \\ t\bar{p}tq\bar{t}, \\ t\bar{p}tqt\bar{p}tq\bar{t}, \\ t\bar{p}tqtpt \\ \dots \end{array} \right\}$$

Decision procedure

CF-GKAT automata

```
if  $t$  and  $x = 1$  then  
   $x := 2$ ;  
  L:  
   $p$ ;  
else  
   $x := 1$ ;  
  goto L;
```

$\mapsto$



Decision procedure

Translating to CF-GKAT automata

Theorem (Zhang, K., Narváez & Naus '25)

For every CF-GKAT expression e , we can construct a GKAT automaton A_e such that $\llbracket e \rrbracket = \llbracket A_e \rrbracket$.

Another syntax-directed translation, à la (Thompson 1968).

Lemma

A_e is linear in the size of e and $|I|$.



Validation

Blinding

C programs are still not CF-GKAT programs:

- ▶ Parsing C can be really hard!
- ▶ Same statements mapped to same variable.
- ▶ Which variables are indicators?
- ▶ Macros may hide relevant information.



LLVM/clang to the rescue

Validation

Blinding

```
#define hidden(x) \  
    x=f(x); goto R;
```

```
int foo(int x, int y) {  
    L:  
    if (x == y) {  
        x = f(x);  
        hidden(x);  
    }  
    return;  
    R:  
    if (x != y) {  
        y = g(y);  
        goto L;  
    }  
}
```

$\mapsto$

```
L:  
if t then  
    | p;  
    | goto R;  
return;  
R:  
if not t then  
    | q;  
    | goto L;
```

Validation

Working on coreutils

We chose to work on `mp_factor_using_pollard_rho`:

- ▶ 91 lines of code (before macro expansion)
- ▶ loops nested three levels deep
- ▶ has a `break` statement inside
- ▶ also contains a `goto` for error handling
- ▶ no indicator variables (yet)

First experiment:

- ▶ Blind, compile (clang), and then decompile (Ghidra).
- ▶ Decompiled code has 3 more goto's and labels.
- ▶ Some manual effort to remove decompilation artifacts.
- ▶ Compare original code to decompiled code: OK.

Second experiment:

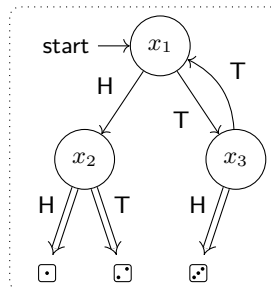
- ▶ Blind, then eliminate goto using indicators (Erosa & Hendren 1994, Cassé et al. 2002)
- ▶ Some manual effort to make indicator detection work.
- ▶ Compare original code to refactored code: OK.

See (Zhang, K., Narváez & Naus '25) for more.

Knuth-Yao algorithm

How to simulate  using   ?

```
while true do
  if flip(0.5) then
    if flip(0.5) then
      return 1 // heads-heads
    else
      return 2 // heads-tails
  else
    if flip(0.5) then
      return 3 // tails-heads
    else
      skip // tails-tails
  end
```



Correctness of Knuth-Yao in ProbGKAT

```
while true do
  if flip(0.5) then
    if flip(0.5) then
      return 1 // heads-heads
    else
      return 2 // heads-tails
  else
    if flip(0.5) then
      return 3 // tails-heads
    else
      skip // tails-tails
  end
end
```



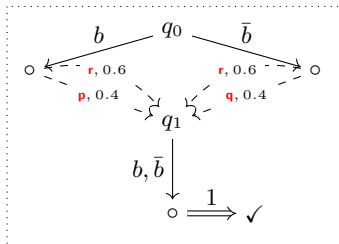
?
≡

```
if flip(1/3) then
  return 1
else
  if flip(0.5) then
    return 2
  else
    return 3
  end
end
```



See (Różowski, K., Kozen, Schmid & Silva '23) for more.

Operational model



- Notion of equivalence: coalgebraic bisimulation
- Can be decided in $O(n^2 \log(n))$ using a generic minimization algorithm (Wißmann et al. '20)

Thanks to ...

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Todd Schmid



Alexandra Silva



Steffen Smolka



Cheng Zhang

