

On propositional program equivalence

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Program equivalence

```
if x = 1 then  
| y++;  
else  
| z := z/2;  
end
```

≡

```
if x ≠ 1 then  
| z := z/2;  
else  
| y++;  
end
```

Propositional program equivalence

```
if b then  
| p;  
else  
| q;  
end
```

≡

```
if not b then  
| q;  
else  
| p;  
end
```

Program equivalence

```
s := new stack();
node := root;
while node != nil do
    s.push(node);
    node := node.left;
end
while !s.empty do
    node = s.pop();
    visit(node);
    node = node.right;
    while node != nil do
        s.push(node);
        node := node.left;
    end
end
```

≡

```
s := new stack();
node := root;
while node != nil or !s.empty do
    if node != nil then
        s.push(node);
        node = node.left;
    else
        node = s.pop();
        visit(node);
        node = node.right;
    end
end
```

(courtesy of Hendrik Jan Hoogeboom)

Propositional program equivalence

```
s;  
while b do  
| p;  
end  
while c do  
| q;  
| while b do  
| | p;  
| end  
end
```

≡

```
s;  
while b or c do  
| if b then  
| | p;  
| else  
| | q;  
| end  
end
```

Guarded Kleene Algebra with Tests (GKAT)

Fix a set $\{p, q, \dots\}$ of **actions** and a Boolean algebra $\{b, c, \dots\}$ of **tests**

$$\text{Exp} \ni e, f ::= \mathbf{assert}\ b \mid p \in \Sigma \mid e; f \mid \mathbf{if}\ b \ \mathbf{then}\ e \ \mathbf{else}\ f \mid \mathbf{while}\ b \ \mathbf{do}\ e$$

- ▶ Language semantics in terms of *guarded strings*.
- ▶ Language equivalence is efficiently decidable! (nearly linear)

(Kozen & Tseng 2008), (Smolka et al. 2020)

GKAT semantics

Guarded strings

Inherited from KAT: sets of *guarded strings*, i.e., words of the form

$$\alpha_1 p_1 \alpha_2 p_2 \alpha_3 p_3 \cdots \alpha_n p_n \alpha_{n+1}$$

where the *atom* $\alpha_i \in \text{At}$ tells us the truth value of each test at point i .

GKAT semantics

By example

$$\left[\begin{array}{l} \text{if } b \text{ then} \\ | \quad p; \\ \text{else} \\ | \quad q; \\ \text{end} \end{array} \right] = \left\{ \begin{array}{l} bp b, \\ bp \bar{b}, \\ \bar{b} qb, \\ \bar{b} qb \end{array} \right\}$$

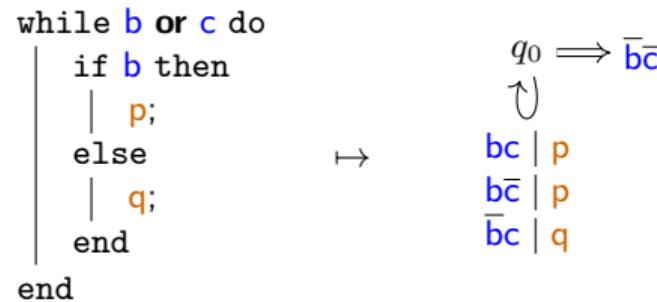
GKAT semantics

By example

$$\left[\begin{array}{l} \text{while } b \text{ or } c \text{ do} \\ | \\ \text{if } b \text{ then} \\ | \\ p; \\ | \\ \text{else} \\ | \\ q; \\ | \\ \text{end} \\ | \\ \text{end} \end{array} \right] = \left\{ \begin{array}{l} \bar{bc}, \\ \bar{bcq}\bar{bc}, \\ \bar{bc}\bar{p}\bar{bcq}\bar{bc}, \\ \dots \end{array} \right\}$$

GKAT decision procedure

Translating to GKAT automata



See (Smolka et al. 2020) for the full details.

GKAT decision procedure

GKAT automata equivalence

Theorem (Smolka et al. '20)

For every GKAT expression e , we can construct a GKAT automaton A_e such that $\llbracket e \rrbracket = \llbracket A_e \rrbracket$.

This is a basic syntax-directed translation, à la (Thompson 1968).

Lemma

A_e is at most linear in the size of e .

Equivalence (bisimilarity) of GKAT automata can be easily decided.

Goto removal

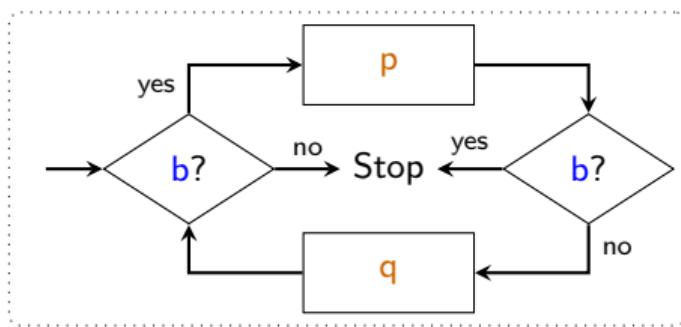
```
L:  
if b then  
| p;  
| goto R;  
return;  
R:  
if not b then  
| q;  
| goto L;  
return;
```

goto removal
(e.g., calipso)

```
x := 1;  
while x ≠ 0 do  
| if x = 1 and b  
| then  
| | p;  
| | x := 2;  
| else if x = 2 and  
| | not b then  
| | | q;  
| | | x := 1;  
| | else  
| | | x := 0;  
| end
```

See (Erosa & Hendren '94; Cassé et al. '02)

Decompilation



```
while b do  
| p;  
| if b then  
| | break;  
| q;  
end
```

Enter CF-GKAT

Fix sets of:

- ▶ *actions* $p \in \Sigma$;
- ▶ *tests* $b \in T$;
- ▶ *labels* $\ell \in L$; and
- ▶ *indicator values* $i \in I$.

CF-GKAT is GKAT augmented with non-local flow control:

$$\begin{aligned} \text{Exp} \ni e, f ::= & \mathbf{assert} \ b \mid p \in \Sigma \mid x := i \ (i \in I) \mid e; f \mid \mathbf{if} \ b \ \mathbf{then} \ e \ \mathbf{else} \ f \mid \\ & \mathbf{while} \ b \ \mathbf{do} \ e \mid \mathbf{break} \mid \mathbf{return} \mid \mathbf{goto} \ \ell \ (\ell \in L) \mid \mathbf{label} \ \ell \ (\ell \in L) \end{aligned}$$

CF-GKAT semantics

By example

```
[[while b do  
  | p;  
  | if b then  
  |   | break;  
  | q;  
| end]] = { bp-qb-,  
           bp-qbpb-qb-,  
           bp-pb,  
           bp-qbpbpb  
           ... }
```

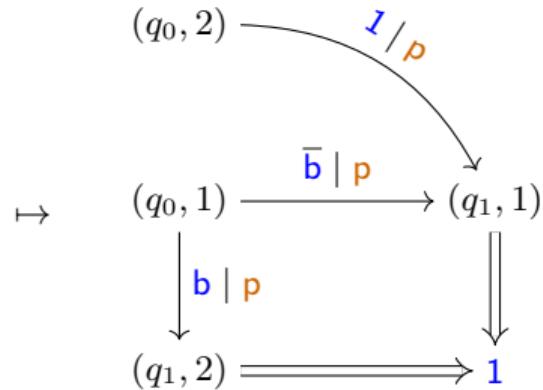
```
L:  
if b then  
  | p;  
  | goto R;  
return;  
R:  
if not b then  
  | q;  
  | goto L;  
return;
```

= { bp⁻b,
 bp⁻qb⁻,
 bp⁻qbpb⁻qb⁻,
 bp⁻qbpb
 ... }

Decision procedure

CF-GKAT automata

```
if b and x = 1 then
  |   x := 2;
  |   L:
  |   p;
else
  |   x := 1;
  |   goto L;
```



Decision procedure

Translating to CF-GKAT automata

Theorem (Zhang, K., Narváez & Naus '25)

For every CF-GKAT expression e , we can construct a GKAT automaton A_e such that $\llbracket e \rrbracket = \llbracket A_e \rrbracket$.

Another syntax-directed translation, à la (Thompson 1968).

Lemma

A_e is linear in the size of e and $|I|$.



Validation

Blinding

C programs are still not CF-GKAT programs:

- ▶ Parsing C can be really hard!
- ▶ Same statements mapped to same variable.
- ▶ Which variables are indicators?
- ▶ Macros may hide relevant information.



LLVM/clang to the rescue

Validation

Blinding

```
#define hidden(x) \
    x=f(x); goto R;

int foo(int x, int y) {
    L:
    if (x == y) {
        x = f(x);
        hidden(x);
    }
    return;
R:
    if (x != y) {
        y = g(y);
        goto L;
    }
}
```

↔

```
L:
if b then
| p;
| goto R;
return;

R:
if not b then
| q;
| goto L;
```

Validation

Working on coreutils

We chose to work on `mp_factor_using_pollard_rho`:

- ▶ 91 lines of code (before macro expansion)
- ▶ loops nested three levels deep
- ▶ has a **break** statement inside
- ▶ also contains a **goto** for error handling
- ▶ no indicator variables (yet)

Validation

Working on coreutils

First experiment:

- ▶ Blind, compile (clang), and then decompile (Ghidra).
- ▶ Decompiled code has 3 more goto's and labels.
- ▶ Some manual effort to remove decompilation artifacts.
- ▶ Compare original code to decompiled code: OK.

Validation

Working on coreutils

Second experiment:

- ▶ Blind, then eliminate **goto** using indicators (Erosa & Hendren 1994, Cassé et al. 2002)
- ▶ Some manual effort to make indicator detection work.
- ▶ Compare original code to refactored code: OK.

See (Zhang, K., Narváez & Naus '25) for more.

Expressivity

```
while b do
    p;
    if b then
        break;
    p;
end
```

Theorem (Schmid, K., Kozen & Silva '21)

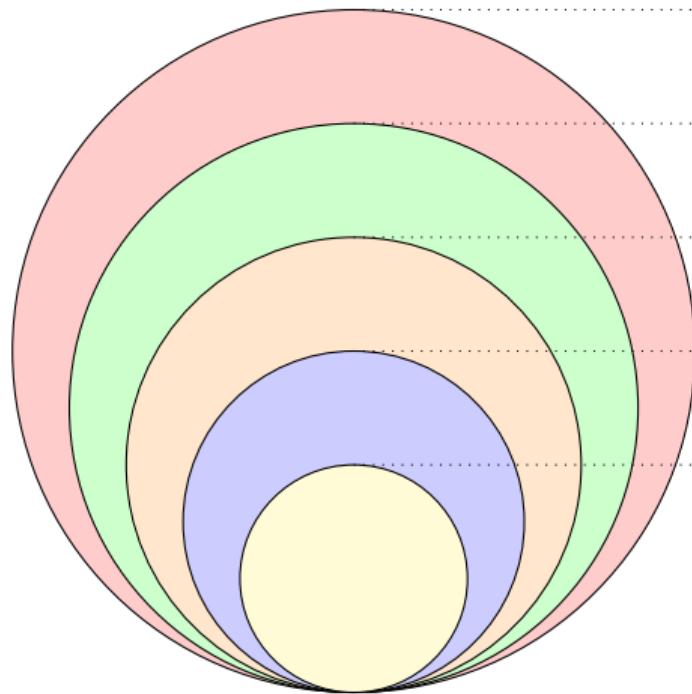
There is no program e built using

- ▶ if-then-else;
- ▶ while-do; and
- ▶ sequential composition

equivalent to the program on the left.

See also (Knuth & Floyd '71; Ashcroft & Manna '72; Peterson et al. '73; Kosaraju '74; Kozen & Tseng '08).

A hierarchy



KAT: $e \cdot f, e + f, e^*$

deterministic KAT

GKAT + repeat e while b changes + ???

GKAT + repeat e while b changes

GKAT: $e \cdot f, \text{if } b \text{ then } e \text{ else } f, \text{while } b \text{ do } e$

A hierarchy

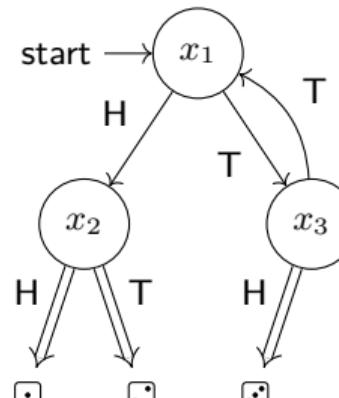
Theorem (Ten Cate & K. '25)

For any deterministic fragment of KAT generated by finitely many operators (e.g., $e \cdot f$, if b then e else f , while b do e), there exist a deterministic KAT expression outside this fragment.

Knuth-Yao algorithm

How to simulate  using  ?

```
while true do
    if flip(0.5) then
        if flip(0.5) then
            | return 1 // heads-heads
        else
            | return 2 // heads-tails
    else
        if flip(0.5) then
            | return 3 // tails-heads
        else
            | skip // tails-tails
end
```



Correctness of Knuth-Yao in ProbGKAT

```
while true do
    if flip(0.5) then
        if flip(0.5) then
            | return 1 // heads-heads
        else
            | return 2 // heads-tails
    else
        if flip(0.5) then
            | return 3 // tails-heads
        else
            | skip // tails-tails
end
```



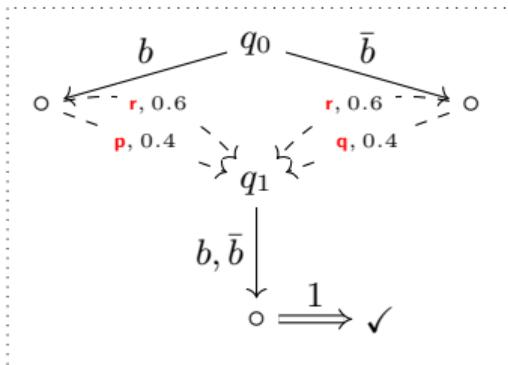
?
≡

```
if flip(1/3) then
    return 1
else
    if flip(0.5) then
        return 2
    else
        return 3
end
```



See (Różowski, K., Kozen, Schmid & Silva '23) for more.

Operational model



- ▶ Notion of equivalence: coalgebraic bisimulation
- ▶ Can be decided in $O(n^2 \log(n))$ using a generic minimization algorithm (Wißmann, Dorsch, Milius & Schröder '20)

Thanks to ...

Balder ten Cate



Nate Foster



Justin Hsu



Dexter Kozen



David Narváez



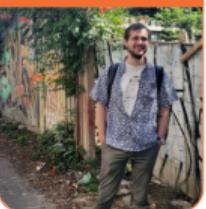
Nico Naus



Wojciech Różowski



Todd Schmid



Alexandra Silva



Steffen Smolka



Cheng Zhang

